



# Construction Products Regulation: EU (No) 305/2011

This Declaration has been drawn-up in accordance with Commission Delegated Regulation (EU) No. 574/2014 which amends Annex III of Regulation (EU) No 305/2011.

#### **DECLARATION OF PERFORMANCE**

No. E0071

## 1. Unique identification code of the product-type:

#### Model number and Description:

55000-126 Series 65 Conventional Class BR Heat Detector with Flashing LED

### **Approved Accessories:**

45681-200,45681-201,45681-245,4581-246,45681-247,45681-248 Bases

## **Harmonised Product Type(s):**

Heat Detectors - Point Detectors

#### 2. Intended use/es:

Point detectors for use in fire detection and fire alarm systems installed in and around buildings

#### 3. Manufacturer:

Apollo Fire Detectors Ltd, 36 Brookside Road, Havant, Hampshire, PO9 1JR, United Kingdom

#### 4. Authorised representative:

Apollo Gesellschaft für Meldetechnologie mbH Am Anger 31 33332 Gütersloh Deutschland

## 5. System(s) of AVCP

System 1

## 6 Harmonised Standard(s)

EN 54-5:2017 + A1:2018

# Notified Body/ies:

DBI Certification A/S (Notified Body 2531)

A HALMA COMPANY







**Apollo Fire Detectors Limited** 

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## 7. Declared performance

## Model Reference:

Table 1

| Detector Category<br>(Heat Class): | Typical Application<br>Temperature | Maximum Application<br>Temperature °C | Minimum Static<br>Response<br>Temperature °C | Maximum Static<br>Response Temperature<br>°C |
|------------------------------------|------------------------------------|---------------------------------------|--|--|
| BR                                 | 40                                 | 65                                    | 69   | 85   |

# Table 2- Response time limits

| Rate of rise of air temperature | Cat BR |          |            |    |
|---------------------------------|--------|----------|------------|----|
| K min-1                         | Lowe   | er limit | Uper limit |    |
|                                 | Min    | S        | Min        | S  |
| 1                               | 29     | 0        | 46         | 0  |
| 3                               | 7      | 13       | 16         | 0  |
| 5                               | 4      | 9        | 10         | 0  |
| 10                              | 2      | 0        | 5          | 30 |
| 20                              | 1      | 30       | 3          | 13 |
| 30                              |        | 40       | 2          | 25 |

## Performance

| Essential characteristics                     | Clauses in<br>EN 54-5:2017/<br>A1:2018 | Regulatory classes | Performance  |
|---|--|--------------------|--|
| Operational reliability:                      |  |                    |  |
| Position of heat sensitive element            | 4.2.1                                  |                    | The heat sensitive element(s) or at least part of it, except elements with auxiliary functions (e.g.characteristic correctors), are a distance ≥15mm from the mounting surface of the point heat detector.   |
| Individual alarm indication                   | 4.2.2                                  | BR                 | Category BR The heat detector is provided with an integral red visual indicator and can remain identified until the alarm is reset. The visual indicator is visible from a distance of 6 m directly below the point heat detector, in an ambient light intensity up to 500 lx. |
| Connection of ancillary devices               | 4.2.3                                  |                    | Open or short circuit failures of connection to ancillary device do not prevent the correct operation of the detector  |
| Monitoring of detachable point heat detectors | 4.2.4                                  |                    | A fault condition is signaled when the detector is removed from the mounting base.   |



| Manufacturer's adjustments                          | 4.2.5 | It is not possible to change the maufacture's settings expept by special means (e.g. a special code or tool, or by breaking or remove a seal).   |
|---|-------|--|
| Onsite adjustments of response behavior             | 4.2.6 | The response behaviour cannot be modified.   |
| Software controlled detectors (when provided)       | 4.2.7 | The detector does not incorporate any software controlled components.  |
| Nominal activation conditions/Sensitivity:          |       |  |
| Directional dependence                              | 4.3.1 | The response time of the point dectetor do not unduly depend on the direction of airflow around the point heat detector.   |
| Static response temperature                         | 4.3.2 | The response temperatures of the point heat detectors lie between the minimum and maximum static response temperatures, according to the category of the point heat detector in Table 1 above.   |
| Response times from typical application temperature | 4.3.3 | The response times of the point heat detector lie between the lower and upper response time limits for the appropriate point heat detector category in Table 2 above.  |
| Response times from 25 °C                           | 4.3.4 | The response time at 3 K min <sup>-1</sup> exceeds 7 min 13 s and the response time at 20 K min <sup>-1</sup> exceeds 1 min 0 s.   |
| Response times from high ambient temperature        | 4.3.5 | No alarm or fault signal was given at high ambient temperatures appropriate to the anticipated service temepratures.  BR  3 K min <sup>-1</sup> , Lower limit, 1 min 20 s and upper limit 16 m. 20 K min <sup>-1</sup> , Lower limit, 12 s and upper limit 3 m 13 s. |
| Reproducibility                                     | 4.3.6 | The response times of the point heat detectors lie between the lower ad upper response time limits specified in Table 2 above.   |
| Response delay (response time):                     |       |  |
| Additional test for suffix S point heat detectors   | 4.4.1 | N/A  |
| Additional test for suffix R point heat detectors   | 4.4.2 | Suffix R, the point heat detector maintains the response requirements of its category, in table 2 above, for high rates of rise of temperature from an initial temperature below the typical application temperature applicable to the category marked on it.        |
|   |       | Point heat detector Initial conditioning category temperature °C   |
|   |       | BR 20 ±2   |
| Tolerance to supply voltage:                        |       |  |
| Variation in supply parameters                      | 4.5   | The point heat detector does not unduly depent on variation in the supply parameters and lie between the lower and upper response time limits specified in Table 2 above.  |



| Durability of nominal activation                         |          |   |
|--|----------|---|
| conditions/Sensitivity:                                  |          |   |
| temperature resistance                                   |          |   |
| Cold (operational)                                       | 4.6.1.1  | No alarm or fault signal was given during the transition to the conditioning temperature or during the period at the condition temperature  |
|  |          | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. |
|  |          | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6                         |
| Dry heat (endurance)                                     | 4.6.1.2  | No fault signal was given on reconnection attributable to the endurance conditioning  |
|  |          | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. |
|  |          | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6                         |
| Humidity resistance                                      |          |   |
| Damp heat, cyclic<br>(operational)                       | 4.6.2.1  | No alarm or fault signal was given during the conditioning.   |
|  |          | Lower temperature: (25±3) °C<br>Upper temperature: (40±2) °C  |
|  |          | Relative humidity: At lower temperature :≥ 95 % At upper temperature : (93 ±3) %  |
|  |          | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. |
|  |          | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6                         |
| Damp heat, steady-state (endurance)                      | 4.6.2.2  | No fault signal was given on reconnection attributable to the endurance conditioning.   |
|  |          | Conditioning Temperature: 40 ±2 °C Relative Humidity: 93 ±3 % Duration: 21 days   |
|  |          | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. |
|  |          | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6                         |
| Corrosion resistance                                     |          |   |
| Sulphur dioxide (SO <sub>2</sub> ) corrosion (endurance) | 4.6.3    | No fault signal was given on reconnection attributable to the endurance conditioning.   |
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|  |         | Conditioning Temperature: 25 ±2 °C Relative Humidity: 93 ±3 % SO2 concentration: 25 ±5 ppm (by volume) Duration: 21 days  Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.  BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed |
|--|---------|--|
|  |         | 30 s compared with the time obtained in 4.3.6  |
| Vibration resistance Shock (operational) | 4.6.4.1 | No alarm or fault signal was given during the conditioning period or an additional 2 min.  |
|  |         | For specimen with a mass ≤ 4,75 kg:  |
|  |         | Shock pulse type: Half sine Pulse duration: 6 ms Peak acceleration: 10X (100-20M) ms-2 (M is specimen mass in Kg) Number of directions: 6 Pulses per direction: 3  |
|  |         | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.  |
|  |         | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6  |
| Impact (operational)                     | 4.6.4.2 | No alarm or fault signal was given during the conditioning period or an additional 2 min.  |
|  |         | Conditioning: Impact energy: 1,9 ±0,1 J Hammer velocity: 1,5 ±0,13 ms <sup>-1</sup> Number of impacts: 1   |
|  |         | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.  |
|  |         | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6  |
| Vibration, sinusoidal<br>(operational)   | 4.6.4.3 | No fault signal was given during the conditioning Conditioning: Frequency range: 10 to 150 Hz Acceleration amplitude: 5 ms⁻²(≈0,5 gn) Number of axes: 3 Sweep rate: 1 octave min⁻¹ Number of sweep cycles: 1 per axis  |
|  |         | Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.  |
|  |         | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6  |



| Vibration, sinusoidal (endurance)               | 4.6.4.4 | No fault signal was given on reconnection attributable to the endurance conditioning.  |
|---|---------|--|
| (chadrance)                                     |         | Conditioning: Frequency range: 10 to 150 Hz Acceleration amplitude: 10 ms <sup>-2</sup> (≈1,0 g <sub>n</sub> ) Number of axes: 3 Sweep rate: 1 octave min <sup>-1</sup> Number of sweep cycles: 20 per axis  Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s |
|   |         | and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.  BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6   |
| Electrical stability EMC immunity (operational) | 4.6.5   | Compliance in EN 50130-4:2011 and No fault signal was given during the conditioning.  Response time at 3 K min <sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.  |
|   |         | BR: 20 K min <sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6  |



### 8. Online Display Location

This document can be viewed online at www.apollo-fire.co.uk

The performance of the product identified above is in conformity with the set of declared performance/s. This declaration of performance is issued, in accordance with Regulation (EU) No. 305/2011, under the sole responsibility of the manufacturer identified above

Signed for and on behalf of Apollo Fire Detectors Limited by:

Mr. David Robbins Technical Director Havant – 27.10.2022

(v7)

