



By Appointment to  
Her Majesty The Queen  
Manufacturers of Fire Detection & Alarm Products  
Apollo Fire Detectors Limited  
Hampshire



**Construction Products Regulation:  
EU (No) 305/2011**

This Declaration has been drawn-up in accordance with Commission Delegated Regulation (EU) No. 574/2014 which amends Annex III of Regulation (EU) No 305/2011.

**DECLARATION OF PERFORMANCE**

**No. E0040**

**1. Unique identification code of the product-type:**

**Model number and Description:**

ORB-HT-51149 Orbis Intrinsically Safe Class BR Heat Detector with SensAlert/FasTest  
ORB-HT-51150 Orbis Intrinsically Safe Class BR Heat Detector with Flashing LED/SensAlert/FasTest

**Approved Accessories:**

Base: ORB-MB-50018, ORB-BA-50008, 45681-207

**Harmonised Product Type(s):**

Heat Detectors – Point Detectors

**2. Intended use/es:**

Point detectors for use in fire detection and fire alarm systems installed in and around buildings

**3. Manufacturer:**

Apollo Fire Detectors Ltd,  
36 Brookside Road, Havant, Hampshire, PO9 1JR, United Kingdom

**4. Authorised representative:**

Apollo Gesellschaft für Meldetechnologie mbH  
Am Anger 31  
33332 Gütersloh  
Deutschland

**5. System of AVCP**

System 1

**6a. Harmonised Standard(s)**

EN 54-5:2017 + A1:2018

**6b. Notified Body:**

DBI Certification A/S (Notified Body 2531)

A HALMA COMPANY



**Apollo Fire Detectors Limited**

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Apollo Fire Detectors Ltd. Registered in England No. 1483208  
Registered Office: 36 Brookside Road, Havant, Hampshire, PO9 1JR VAT Registration No. GB 339 0553 54

## 7. Declared performance

**Table 1**

| Detector Category (Heat Class): | Typical Application Temperature | Maximum Application Temperature °C | Minimum Static Response Temperature °C | Maximum Static Response Temperature °C |
|---------------------------------|---------------------------------|------------------------------------|--|--|
| BR                              | 40                              | 65                                 | 69                                     | 85                                     |

**Table 2- Response time limits**

| Rate of rise of air temperature K min-1 | Cat BR      |    |            |    |
|---|-------------|----|------------|----|
|   | Lower limit |    | Uper limit |    |
|   | Min         | S  | Min        | S  |
| 1                                       | 29          | 0  | 46         | 0  |
| 3                                       | 7           | 13 | 16         | 0  |
| 5                                       | 4           | 9  | 10         | 0  |
| 10                                      | 2           | 0  | 5          | 30 |
| 20                                      | 1           | 30 | 3          | 13 |
| 30                                      |             | 40 | 2          | 25 |

### Performance

| Essential characteristics                     | Clauses in EN 54-5:2017/ A1:2018 | Regulatory classes | Performance  |
|---|----------------------------------|--------------------|--|
| <b>Operational reliability:</b>               |                                  |                    |  |
| Position of heat sensitive element            | 4.2.1                            | BR                 | The heat sensitive element(s) or at least part of it, except elements with auxiliary functions (e.g.characteristic correctors), are a distance $\geq 15$ mm from the mounting surface of the point heat detector.  |
| Individual alarm indication                   | 4.2.2                            |                    | Category BR<br>The heat detector is provided with an integral red visual indicator and can remain identified until the alarm is reset. The visual indicator is visible from a distance of 6 m directly below the point heat detector,in an ambient light intensity up to 500 lx. |
| Connection of ancillary devices               | 4.2.3                            |                    | Open or short circuit failures of connection to ancillary device do not prevent the correct operation of the detector  |
| Monitoring of detachable point heat detectors | 4.2.4                            |                    | A fault condition is signaled when the detector is removed from the mounting base.   |
| Manufacturer's adjustments                    | 4.2.5                            |                    | It is not possible to change the manufacture's settings except by special means (e.g. a special code or tool, or by breaking or remove a seal).  |

| Onsite adjustments of response behavior             | 4.2.6                               |  | N/A   |                              |                                     |    |       |
|---|-------------------------------------|--|---|------------------------------|-------------------------------------|----|-------|
| Software controlled detectors (when provided)       | 4.2.7                               |  | The software documentation and the software design complies supplied by the manufacturer with the requirements of this standard.  |                              |                                     |    |       |
| <b>Nominal activation conditions/Sensitivity:</b>   |                                     |  |   |                              |                                     |    |       |
| Directional dependence                              | 4.3.1                               |  | The response time of the point detector do not unduly depend on the direction of airflow around the point heat detector.  |                              |                                     |    |       |
| Static response temperature                         | 4.3.2                               |  | The response temperatures of the point heat detectors lie between the minimum and maximum static response temperatures, according to the category of the point heat detector in Table 1 above.  |                              |                                     |    |       |
| Response times from typical application temperature | 4.3.3                               |  | The response times of the point heat detector lie between the lower and upper response time limits for the appropriate point heat detector category in Table 2 above.   |                              |                                     |    |       |
| Response times from 25 °C                           | 4.3.4                               |  | The response time at 3 K min <sup>-1</sup> exceeds 7 min 13 s and the response time at 20 K min <sup>-1</sup> exceeds 1 min 0 s.  |                              |                                     |    |       |
| Response times from high ambient temperature        | 4.3.5                               |  | No alarm or fault signal was given at high ambient temperatures appropriate to the anticipated service temperatures.<br><br>BR<br>3 K min <sup>-1</sup> , Lower limit, 1 min 20 s and upper limit 16 m.<br>20 K min <sup>-1</sup> , Lower limit, 12 s and upper limit 3 m 13 s.   |                              |                                     |    |       |
| Reproducibility                                     | 4.3.6                               |  | The response times of the point heat detectors lie between the lower ad upper response time limits specified in Table 2 above.  |                              |                                     |    |       |
| <b>Response delay (response time):</b>              |                                     |  |   |                              |                                     |    |       |
| Additional test for suffix S point heat detectors   | 4.4.1                               |  | N/A   |                              |                                     |    |       |
| Additional test for suffix R point heat detectors   | 4.4.2                               |  | Suffix R, the point heat detector maintains the response requirements of its category, in table 2 above, for high rates of rise of temperature from an initial temperature below the typical application temperature applicable to the category marked on it.<br><br><table border="1" data-bbox="774 1534 1337 1675"> <thead> <tr> <th>Point heat detector category</th> <th>Initial conditioning temperature °C</th> </tr> </thead> <tbody> <tr> <td>BR</td> <td>20 ±2</td> </tr> </tbody> </table> | Point heat detector category | Initial conditioning temperature °C | BR | 20 ±2 |
| Point heat detector category                        | Initial conditioning temperature °C |  |   |                              |                                     |    |       |
| BR  | 20 ±2                               |  |   |                              |                                     |    |       |
| <b>Tolerance to supply voltage:</b>                 |                                     |  |   |                              |                                     |    |       |
| Variation in supply parameters                      | 4.5                                 |  | The point heat detector does not unduly depend on variation in the supply parameters and lie between the lower and upper response time limits specified in Table 2 above.   |                              |                                     |    |       |

|   |         |  |
|---|---------|--|
| <b>Durability of nominal activation conditions/Sensitivity:</b> |         |  |
| temperature resistance  |         |  |
| Cold (operational)  | 4.6.1.1 | <p>No alarm or fault signal was given during the transition to the conditioning temperature or during the period at the condition temperature</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>  |
| Dry heat (endurance)  | 4.6.1.2 | <p>No fault signal was given on reconnection attributable to the endurance conditioning</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>  |
| Humidity resistance   |         |  |
| Damp heat, cyclic (operational)                                 | 4.6.2.1 | <p>No alarm or fault signal was given during the conditioning.</p> <p>Lower temperature: (25±3) °C<br/>Upper temperature: (40±2) °C</p> <p>Relative humidity:<br/>At lower temperature : ≥ 95 %<br/>At upper temperature : (93 ±3) %</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p> |
| Damp heat, steady-state (endurance)                             | 4.6.2.2 | <p>No fault signal was given on reconnection attributable to the endurance conditioning.</p> <p>Conditioning<br/>Temperature : 40 ±2 °C<br/>Relative Humidity: 93 ±3 %<br/>Duration : 21 days</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>  |
| Corrosion resistance  |         |  |
| Sulphur dioxide (SO <sub>2</sub> ) corrosion (endurance)        | 4.6.3   | No fault signal was given on reconnection attributable to the endurance conditioning.  |

|                                     |         |   |
|-------------------------------------|---------|---|
|                                     |         | <p>Conditioning<br/> Temperature : 25 ±2 °C<br/> Relative Humidity: 93 ±3 %<br/> SO2 concentration: 25 ±5 ppm (by volume)<br/> Duration : 21 days</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>   |
| Vibration resistance                |         |   |
| Shock (operational)                 | 4.6.4.1 | <p>No alarm or fault signal was given during the conditioning period or an additional 2 min.</p> <p>For specimen with a mass ≤ 4,75 kg :</p> <p>Shock pulse type: Half sine<br/> Pulse duration : 6 ms<br/> Peak acceleration: 10X (100-20M) ms<sup>-2</sup> (M is specimen mass in Kg)<br/> Number of directions: 6<br/> Pulses per direction: 3</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p> |
| Impact (operational)                | 4.6.4.2 | <p>No alarm or fault signal was given during the conditioning period or an additional 2 min.</p> <p>Conditioning:<br/> Impact energy: 1,9 ±0,1 J<br/> Hammer velocity: 1,5 ±0,13 ms<sup>-1</sup><br/> Number of impacts: 1</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>  |
| Vibration, sinusoidal (operational) | 4.6.4.3 | <p>No fault signal was given during the conditioning</p> <p>Conditioning:<br/> Frequency range: 10 to 150 Hz<br/> Acceleration amplitude: 5 ms<sup>-2</sup>(≈0,5 g<sub>n</sub>)<br/> Number of axes : 3<br/> Sweep rate: 1 octave min<sup>-1</sup><br/> Number of sweep cycles: 1 per axis</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>  |

|   |         |  |  |
|---|---------|--|--|
| Vibration, sinusoidal (endurance)               | 4.6.4.4 |  | <p>No fault signal was given on reconnection attributable to the endurance conditioning.</p> <p>Conditioning:<br/> Frequency range: 10 to 150 Hz<br/> Acceleration amplitude: 10 ms<sup>-2</sup>(≈1,0 g<sub>n</sub>)<br/> Number of axes : 3<br/> Sweep rate: 1 octave min<sup>-1</sup><br/> Number of sweep cycles: 20 per axis</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p> |
| Electrical stability EMC immunity (operational) | 4.6.5   |  | <p>Compliance in EN 50130-4:2011 and No fault signal was given during the conditioning.</p> <p>Response time at 3 K min<sup>-1</sup> was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.</p> <p>BR: 20 K min<sup>-1</sup> was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6</p>  |

**8. Online Display Location**

This document can be viewed online at [www.apollo-fire.co.uk](http://www.apollo-fire.co.uk)

The performance of the product identified above is in the conformity with the set of declared performance/s. This declaration of performance is issued, in accordance with Regulation (EU) No. 305/2011, under the sole responsibility of the manufacturer identified above

Signed for and on behalf of Apollo Fire Detectors Limited by:



Mr. David Robbins  
Technical Director

Havant – 05.07.2022

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