



Construction Products Regulation: EU (No) 305/2011

This Declaration has been drawn-up in accordance with Commission Delegated Regulation (EU) No. 574/2014 which amends Annex III of Regulation (EU) No 305/2011.

DECLARATION OF PERFORMANCE

No. E0041

1. Unique identification code of the product-type:

Model number and Description:

ORB-HT-51151 Orbis Intrinsically Safe Class BS Heat Detector with SensAlert/FasTest ORB-HT-51152 Orbis Intrinsically Safe Class BS Heat Detector with Flashing LED/SensAlert/FasTest

Approved Accessories:

Base: ORB-MB-50018, ORB-BA-50008, 45681-207

Harmonised Product Type(s):

Heat Detectors - Point Detectors

2. Intended use/es:

Point detectors for use in fire detection and fire alarm systems installed in and around buildings

3. Manufacturer:

Apollo Fire Detectors Ltd, 36 Brookside Road, Havant, Hampshire, PO9 1JR, United Kingdom

4. Authorised representative:

Apollo Gesellschaft für Meldetechnologie mbH Am Anger 31 33332 Gütersloh Deutschland

5. System of AVCP

System 1

6a. Harmonised Standard(s)

EN 54-5:2017 + A1:2018

6b. Notified Body:

DBI Certification A/S (Notified Body 2531)

A HALMA COMPANY



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Apollo Fire Detectors Ltd. Registered in England No. 1483208 Registered Office: 36 Brookside Road, Havant, Hampshire, PO9 1JR VAT Registration No. GB 339 0553 54

7. Declared performance

Table 1				
Detector Category	Typical Application	Maximum Application	Minimum Static	Maximum Static
(Heat Class):	Temperature	Temperature °C	Response	Response Temperature
			Temperature °C	°C
BS	40	65	69	85

Table 2- Response time limits

Rate of rise of air temperature	Cat BS			
K min-1	Lower limit		Uper limit	
	Min	S	Min	S
1	29	0	46	0
3	7	13	16	0
5	4	9	10	0
10	2	0	5	30
20	1	30	3	13
30		40	2	25

Performance

Essential characteristics	Clauses in EN 54-5:2017/ A1:2018	Regulatory classes	Performance
Operational reliability:			
Position of heat sensitive element	4.2.1		The heat sensitive element(s) or at least part of it, except elements with auxiliary functions (e.g.characteristic correctors), are a distance ≥15mm from the mounting surface of the point heat detector.
Individual alarm indication	4.2.2	BS	Category BS The heat detector is provided with an integral red visual indicator and can remain identified until the alarm is reset. The visual indicator is visible from a distance of 6 m directly below the point heat detector, in an ambient light intensity up to 500 lx.
Connection of ancillary devices	4.2.3		Open or short circuit failures of connection to ancillary device do not prevent the correct operation of the detector
Monitoring of detachable point heat detectors	4.2.4	-	A fault condition is signaled when the detector is removed from the mounting base.
Manufacturer's adjustments	4.2.5		It is not possible to change the maufacture's settings expept by special means (e.g. a special code or tool, or by breaking or remove a seal).



Onsite adjustments of	4.2.6	N/A		
response behavior				
Software controlled	4.2.7	The software documentation and the software design		
detectors (when provided)		complies supplied by the manufacturer with the		
		requirements of this standard.		
Nominal activation				
conditions/Sensitivity:				
Directional dependence	4.3.1	The response time of the point dectetor do not unduly		
		depend on the direction of airflow around the point		
		heat detector.		
	4.2.2			
Static response	4.3.2	The response temperatures of the point heat detectors lie		
temperature		between the minimum and maximum static response		
		temperatures, according to the category of the point heat		
		detector in Table 1 above.		
Response times from	4.3.3	The response times of the point heat detector lie		
typical application		between the lower and upper response time limits for		
temperature		the appropriate point heat detector category in Table 2		
		above.		
Response times from 25 °C	4.3.4	The response time at 3 K min ⁻¹ exceeds 7 min 13 s and the		
		response time at 20 K min ⁻¹ exceeds 1 min 0 s.		
Response times from high	4.3.5	No alarm or fault signal was given at high ambient		
ambient temperature		temperatures appropriate to the anticipated service		
		temepratures.		
		BS		
		3 K min ⁻¹ , Lower limit, 1 min 20 s and upper limit 16 m.		
		20 K min ⁻¹ , Lower limit, 12 s and upper limit 3 m 13 s.		
Reproducibility	4.3.6	The response times of the point heat detectors lie		
		between the lower ad upper response time limits		
		specified in Table 2 above.		
Response delay (response				
time):				
Additional test for suffix S	4.4.1	Suffix S point heat detector did not exceed the lower		
point heat detectors		limits of response time during the transer period or		
		during the 10 min exposure below.		
		Point heat Conditioning Airflow		
		detector Temperature °C Temperature °C		
		category		
		BS 20 ±2 65 ±2		
		Rate of rise of air Lower Limit response		
		temperature K min ⁻¹ time		
		Min S		
		3 9 40		
		5 5 48		
		10 2 54		



			20	1	27
				-	2,
			30		58
Additional test for suffix R point heat detectors	4.4.2		N/A		
Tolerance to supply voltage:		-			
Variation in supply parameters	4.5	-	The point heat detect variation in the supp lower and upper rest above.	oly parameters and	lie between the
Durability of nominal activation conditions/Sensitivity:					
temperature resistance Cold (operational)	4.6.1.1		No alarm or fault signal was given during the transition t the conditioning temperature or during the period at the condition temperature		-
			Response time at 3 k and did not exceed 2 obtained in 4.3.6.		
			BS: 20 K min ⁻¹ was no 30 s compared with		
Dry heat (endurance)	4.6.1.2	-	No fault signal was g the endurance cond		ion attributable to
			Response time at 3 k and did not exceed 2 obtained in 4.3.6.		
			BS: 20 K min ⁻¹ was no 30 s compared with		
Humidity resistance		-			
Damp heat, cyclic (operational)	4.6.2.1		No alarm or fault sig conditioning.	nal was given duri	ng the
			Lower temperature: Upper temperature:		
			Relative humidity: At lower temperatur At upper temperatur		
			Response time at 3 k and did not exceed 2 obtained in 4.3.6.		
			BS: 20 K min ⁻¹ was no 30 s compared with		
Damp heat, steady-state (endurance)	4.6.2.2		No fault signal was g the endurance cond		ion attributable to
			Conditioning		



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		Temperature : 40 ±2 °C
		Relative Humidity: 93 ±3 %
		Duration : 21 days
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		BS: 20 K min ⁻¹ was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6
Corrosion resistance		
Sulphur dioxide (SO ₂) corrosion (endurance)	4.6.3	No fault signal was given on reconnection attributable to the endurance conditioning.
		Conditioning Temperature : 25 ±2 °C Relative Humidity: 93 ±3 % SO2 concentration: 25 ±5 ppm (by volume) Duration : 21 days
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		BS: 20 K min ⁻¹ was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6
Vibration resistance		
Shock (operational)	4.6.4.1	No alarm or fault signal was given during the conditioning period or an additional 2 min.
		For specimen with a mass ≤ 4,75 kg :
		Shock pulse type: Half sine Pulse duration: 6 ms
		Peak acceleration: 10X (100-20M) ms-2 (M is specimen
		mass in Kg)
		Number of directions: 6
		Pulses per direction: 3
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		BS: 20 K min ⁻¹ was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6
Impact (operational)	4.6.4.2	No alarm or fault signal was given during the conditioning period or an additional 2 min.
		Conditioning: Impact energy: 1,9 ±0,1 J Hammer velocity: 1,5 ±0,13 ms ⁻¹ Number of impacts: 1
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.



	BS: 20 K min ⁻¹ was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6
4.6.4.3	 No fault signal was given during the conditioning Conditioning: Frequency range: 10 to 150 Hz Acceleration amplitude: 5 ms⁻²(≈0,5 g_n) Number of axes : 3 Sweep rate: 1 octave min⁻¹ Number of sweep cycles: 1 per axis Response time at 3 K min⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. BS: 20 K min⁻¹ was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6
4.6.4.4	 No fault signal was given on reconnection attributable to the endurance conditioning. Conditioning: Frequency range: 10 to 150 Hz Acceleration amplitude: 10 ms⁻²(≈1,0 g_n) Number of axes : 3 Sweep rate: 1 octave min⁻¹ Number of sweep cycles: 20 per axis Response time at 3 K min⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time
465	obtained in 4.3.6. BS: 20 K min ⁻¹ was not less than 1 min and did not exceed 30 s compared with the time obtained in 4.3.6
4.6.5	Compliance in EN 50130-4:2011 and No fault signal was given during the conditioning. Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.



8. Online Display Location

This document can be viewed online at www.apollo-fire.co.uk

The performance of the product identified above is in the conformity with the set of declared performance/s. This declaration of performance is issued, in accordance with Regulation (EU) No. 305/2011, under the sole responsibility of the manufacturer identified above

Signed for and on behalf of Apollo Fire Detectors Limited by:

Mr. David Robbins Technical Director Havant – 05.07.2022

(v8)

