



CERTIFICATE OF CONSTANCY OF PERFORMANCE

Issued by DBI Certification, notified body No. 2531.

In compliance with Regulation 305/2011/EU of the European Parliament and of the Council of 9 March 2011 (the Construction Products Regulation or CPR), this certificate applies to the construction product

Orbis Class A1R Conventional Heat Detectors

The product fulfils the essential characteristic:

See Annex 1

Intended use: Applications related to automatic fire alarm systems

Placed on the market under the name or trade mark of:

Apollo Fire Detectors Ltd. 36 Brookside Road

Havant, Hampshire, GB-P09 1JR

United Kingdom

and produced in the manufacturing plant:

Apollo Fire Detectors Ltd. 36 Brookside Road Havant, Hampshire, GB-P09 1JR United Kingdom

This attests that all provisions concerning the performance described in Annex ZA of the standard(s)

EN 54-5:2017/A1:2018 : Fire detection and fire alarm systems - Part 5: Heat detectors - point heat detectors

under system 1 for the performance set out in this certificate are applied and that the factory production control conducted by the manufacturer is assessed to ensure the

CONSTANCY OF PERFORMANCE OF THE CONSTRUCTION PRODUCT.

This certificate was first issued on 2019-10-09 and will remain valid as long as neither the harmonised standard, the construction product, the AVCP methods nor the manufacturing conditions in the plant are modified significantly, unless suspended or withdrawn by the notified product certification body.

The attached annexes form part of this certificate.

Date of issue: 2022-06-30

(This certificate supersedes the previous version of this certificate issued 2019-10-09)

Merete Poulsen Responsible for evaluation

Responsible for certification decision

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Annex 1

EXTENT

Model Reference:

Orbis Class A1R Conventional Heat Detectors

Variants:

ORB-HT-11001-APO Orbis Class A1R Heat Detector with SensAlert and FasTest

 ${\sf ORB-HT-11013-APO\ Orbis\ Class\ A1R\ Heat\ Detector\ with\ Flashing\ LED,\ SensAlert\ and\ FasTest}$

OEX-HT-11037-APO Orbis Class A1R Heat Detector with Flashing LED and SensAlert

OEX-HT-11089-APO Orbis Class A1R Heat Detector with SensAlert

Bases:

OB: ORB-MB-00001-APO TimeSaver base

OL: ORB-MB-00002-APO TimeSaver base LX (without continuity checking link)

OD: ORB-DB-00003-APO TimeSaver diode base

OR: ORB-RB-10004-APO TimeSaver relay base

XL: ORB-MB-00012-APO & OEX-MB-00016-APO LX bases

EB: ORB-MB-00019-APO TimeSaver deep base

Ancillary:

ORB-BA-10008-APO Adaptor Base (to be used in conjunction with the following bases only: 45681-200 & 45681-201)

Description:

Class A1R Adressable Heat Detector intend for use in fire detection and fire alarm systems intalled in and around buldings. With additional test for Suffix R detectors.

Operating Voltage:

8.5 to 33 V DC

Heat Response Catergory:

*For detector categories with the suffix S or R, additional requirements are needed see 4.4.1 or 4.4.2

Table 1

Detector Category (Heat Class):	Typical Application Temperature	Maximum Application Temperature °C	Minimum Static Response Temperature °C	Maximum Static Response Temperature °C
A1R	25	50	54	65

Table 2- Response time limits

Tubic 2 Response						
Rate of rise of						
air temperature K min-1	Lowe	r limit	Upe	er limit		
K 2	Min	S	Min	S		
1	29	0	40	20		
3	7	13	13	40		
5	4	9	8	20		
10	1	0	4	20		
20		30	2	20		
30		20	1	40		



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Essential characteristics	Clauses in EN 54-5:2017/ A1:2018	Regulatory classes	Performance
Operational reliability:			
Position of heat sensitive element	4.2.1		The heat sensitive element(s) or at least part of it, except elements with auxiliary functions (e.g.characteristic correctors), are a distance ≥15mm from the mounting surface of the point heat detector.
Individual alarm indication	4.2.2		Category A1R The heat detector is provided with an integral red visual indicator and can remain identified until the alarm is reset. The visual indicator is visible from a distance of 6 m directly below the point heat detector, in an ambient light intensity up to 500 lx.
Connection of ancillary devices	4.2.3		Open or short circuit failures of connection to ancillary device do not prevent the correct operation of the detector
Monitoring of detachable point heat detectors	4.2.4		A fault condition is signaled when the detector is removed from the mounting base.
Manufacturer's adjustments	4.2.5		It is not possible to change the maufacture's settings expept by special means (e.g. a special code or tool, or by breaking or remove a seal).
Onsite adjustments of response behavior	4.2.6	A1R	N/A
Software controlled detectors (when provided)	4.2.7	AIN	The software documentation and the software design complies supplied by the manufacturer with the requirements of this standard.
Nominal activation conditions/Sensitivity:]	
Directional dependence	4.3.1		The response time of the point dectetor do not unduly depend on the direction of airflow around the point heat detector.
Static response temperature	4.3.2		The response temperatures of the point heat detectors libetween the minimum and maximum static response temperatures, according to the category of the point heat detector in Table 1 above.
Response times from typical application temperature	4.3.3		The response times of the point heat detector lie between the lower and upper response time limits for the appropriate point heat detector category in Table 2 above.
Response times from 25 °C	4.3.4		The response time at 3 K min ⁻¹ exceeds 7 min 13 s and the response time at 20 K min ⁻¹ exceeds 1 min 0 s.
Response times from high ambient temperature	4.3.5		No alarm or fault signal was given at high ambient temperatures appropriate to the anticipated service temepratures. A1R







Damp heat, cyclic (operational)	4.6.2.1	No alarm or fault signal was given during the conditioning.
Humidity resistance		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
Dry heat (endurance)	4.6.1.2	No fault signal was given on reconnection attributable to the endurance conditioning
		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
Cold (operational)	4.6.1.1	No alarm or fault signal was given during the transition to the conditioning temperature or during the period at the condition temperature
activation conditions/Sensitivity: temperature resistance		
Durability of nominal		above.
parameters		variation in the supply parameters and lie between the lower and upper response time limits specified in Table above.
voltage: Variation in supply	4.5	The point heat detector does not unduly depent on
Tolerance to supply		J 12
		category temperature °C A1R 5 ±2
		initial temperature below the typical application temperature applicable to the category marked on it. Point heat detector Initial conditioning
Additional test for suffix R point heat detectors	4.4.2	Suffix R, the point heat detector maintains the response requirements of its category, in table 2 above, for high rates of rise of temperature from an
Additional test for suffix S point heat detectors	4.4.1	N/A
Response delay (response time):		
Reproducibility	4.3.6	The response times of the point heat detectors lie between the lower ad upper response time limits specified in Table 2 above.
		3 K min ⁻¹ , Lower limit, 1 min 20s and upper limit 13 m 40 20 K min ⁻¹ , Lower limit, 12 s and upper limit 2 m 20 s.



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		Lower temperature: (25±3) °C
		Upper temperature: (40±2) °C
		Relative humidity:
		At lower temperature :≥ 95 %
		At upper temperature : (93 ±3) %
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		0.553
		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
		50 5 compared with the time obtained in 4.5.0
Damp heat, steady-state	4.6.2.2	No fault signal was given on reconnection attributable to
(endurance)	4.0.2.2	
(endurance)		the endurance conditioning.
		Conditioning
		Conditioning
		Temperature: 40 ±2 °C
		Relative Humidity: 93 ±3 %
		Duration : 21 days
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1R: 20 K min-1 was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
Corrosion resistance		
Sulphur dioxide (SO ₂)	4.6.3	No fault signal was given on reconnection attributable to
corrosion (endurance)		the endurance conditioning.
		Conditioning
		Temperature: 25 ±2 °C
		Relative Humidity: 93 ±3 %
		SO2 concentration: 25 ±5 ppm (by volume)
		Duration: 21 days
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
		50 5 compared with the time obtained in 4.5.0
Vibration resistance		
	4.0.4.4	No playm or fault signal was allow that
Shock (operational)	4.6.4.1	No alarm or fault signal was given during the
		conditioning period or an additional 2 min.
		For an adjusting with a superior of 75 l
		For specimen with a mass ≤ 4,75 kg:
		Shock pulse type: Half sine
		Pulse duration: 6 ms
		Peak acceleration: 10X (100-20M) ms-2 (M is specimen
		mass in Kg)
		Number of directions: 6
		Pulses per direction: 3







immunity (operational)		given during the conditioning.
Electrical stability EMC	4.6.5	A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6 Compliance in EN 50130-4:2011 and No fault signal was
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		Number of sweep cycles: 20 per axis
		Number of axes : 3 Sweep rate: 1 octave min ⁻¹
		Acceleration amplitude: 10 ms ⁻² (≈1,0 g _n)
		Conditioning: Frequency range: 10 to 150 Hz
(endurance)		the endurance conditioning.
Vibration, sinusoidal	4.6.4.4	No fault signal was given on reconnection attributable to
		30 s compared with the time obtained in 4.3.6
		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed
		obtained in 4.3.6.
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time
		Number of sweep cycles: 1 per axis
		Sweep rate: 1 octave min ⁻¹
		Acceleration amplitude: 5 ms ⁻² (≈0,5 g _n) Number of axes : 3
(operational)		Frequency range: 10 to 150 Hz
Vibration, sinusoidal (operational)	4.6.4.3	No fault signal was given during the conditioning Conditioning:
		30 s compared with the time obtained in 4.3.6
		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed
		obtained in 4.3.6.
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time
		Number of impacts: 1
		Impact energy: 1,9 ±0,1 J Hammer velocity: 1,5 ±0,13 ms ⁻¹
		Conditioning:
impact (operational)	7.0.4.2	conditioning period or an additional 2 min.
Impact (operational)	4.6.4.2	No alarm or fault signal was given during the
		A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
		obtained in 4.3.6.
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time







	Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. A1R: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6

Annex 2

TEST DOCUMENTATION

Accredited Laboratory	Report no.	Date
BRE	211499	2004-01-05
BRE	TE 210363 SW	2003-05-01
BRE	TE 211499 SW/A	2004-12-22
BRE	TE 211499 SW/B	2004-03-29
BRE	TE P105641-1001 Issue: 1	2018-10-31

TECHNICAL BASIS

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File Number		Title	
400-HT-00001	Build Standard		
400-HT-00002	Build Standard		
ORB-MB-00001	Build Standard no. 300-MA-00	0003	
ORB-MB-00002	Build Standard no. 300-MA-00	0006	
ORB-DB-00003	Build Standard		
ORB-RB-10004	Build Standard no. 400-RB-00	007	
ORB-MB-00012	Build Standard		
ORB-MB-00019	Build Standard no. 300-MA-00	0012	

