

CERTIFICATE OF CONSTANCY OF PERFORMANCE

Issued by DBI Certification, notified body No. 2531.

In compliance with Regulation 305/2011/EU of the European Parliament and of the Council of 9 March 2011 (the Construction Products Regulation or CPR), this certificate applies to the construction product

SA5000-700 Soteria Analogue Addressable Class A1R Optical Smoke/Heat Detector

The product fulfils the essential characteristic:

See Annex 1

Intended use: Applications related to automatic fire alarm systems

Placed on the market under the name or trade mark of:

Apollo Fire Detectors Ltd. 36 Brookside Road Havant, Hampshire, P09 1JR United Kingdom

and produced in the manufacturing plant:

Apollo Fire Detectors Ltd. 36 Brookside Road Havant, Hampshire, P09 1JR United Kingdom

Authorized Representative:

Apollo Gesellschaft für Meldetechnologie mbH

Am Anger 31 33332 Gütersloh Germany

This attests that all provisions concerning the performance described in Annex ZA of the standard(s)

EN 54-5:2017/A1:2018 : Fire detection and fire alarm systems - Part 5: Heat detectors - point heat

detectors

EN 54-7:2018 : Fire detection and fire alarm systems - part 7: Smoke detectors - Point smoke

detectors that operate using scattered light, transmitted light or ionization

under system 1 for the performance set out in this certificate are applied and that the factory production control conducted by the manufacturer is assessed to ensure the

CONSTANCY OF PERFORMANCE OF THE CONSTRUCTION PRODUCT.

This certificate was first issued on 2019-10-10 and will remain valid as long as neither the harmonised standard, the construction product, the AVCP methods nor the manufacturing conditions in the plant are modified significantly, unless suspended or withdrawn by the notified product certification body.

The attached annexes form part of this certificate.

Date of issue: 2023-03-14.

(This certificate supersedes the previous version of this certificate issued 2019-10-10)

Chris Ellis Responsible for evaluation Merete Poulsen
Responsible for certification decision





Tlf.: 36 34 90 90



Annex 1

EXTENT

Model Reference:

SA5000-700 Soteria Analogue Addressable Class A1R Optical Smoke/Heat Detector

Bases:

SA5000-200 Addressable XPERT 8 Mounting Base

45681-210 XP95 Mounting Base

Modes:

Certified at the following settings:

Mode 1: High sensitivity smoke detector with high heat enhancement

Mode 2: Standard smoke sensitivity only

Mode 3: Medium sensitivity smoke detector with medium heat enhancement

Mode 4: Low sensitivity smoke detector with high heat enhancement

Mode 5: Class A1R heat detector

Description:

Class A1R Adressable Heat and Smoke Detector intend for use in fire detection and fire alarm systems intalled in and around buldings.

Operating Voltage:

17 to 35 V DC

Heat Response Catergory:

*For detector categories with the suffix R, additional requirements are needed see 4.4.2.

Table 1

	Detector Category	Typical Application	Maximum	Minimum Static	Maximum Static
	(Heat Class):	Temperature	Application	Response	Response
			Temperature °C	Temperature °C	Temperature °C
I	A1	25	50	54	65
1					

Table 2- Response time limits

Rate of rise of	Cat A1			
air temperature K min-1	Lowe	r limit	Upe	r limit
	Min	S	Min	S
1	29	0	40	20
3	7	13	13	40
5	4	9	8	20
10	1	0	4	20
20		30	2	20
30		20	1	40







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Essential characteristics	Clauses in EN 54-5:2017/ A1:2018	Regulatory classes	Performance
Operational reliability: Position of heat sensitive element	4.2.1		The heat sensitive element(s) or at least part of it, except elements with auxiliary functions (e.g.characteristic correctors), are a distance ≥15mm from the mounting surface of the point heat detector.
Individual alarm indication	4.2.2		The heat detector is provided with an integral red visual indicator and can remain identified until the alarm is reset. The visual indicator is visible from a distance of 6 m directly below the point heat detector, in an ambient light intensity up to 500 lx.
Connection of ancillary devices	4.2.3		Open or short circuit failures of connection to ancillary device do not prevent the correct operation of the detector
Monitoring of detachable point heat detectors	4.2.4		A fault condition is signaled when the detector is removed from the mounting base.
Manufacturer's adjustments	4.2.5		It is not possible to change the maufacture's settings expept by special means (e.g. a special code or tool, or by breaking or remove a seal).
Onsite adjustments of response behavior	4.2.6		The detector is provided with a provision for an onsite adjustment of the response behavior and the manufacturer declares a corresponding class and adjustment setting:
		A1R	There are adjustable setting(s) which the manufacturer is not stating a corresponding category in accordance to this standard and are only accessible by the use of a code or special tool, and it is clearly marked on the point heat detector or in the associated data.
Software controlled detectors (when provided)	4.2.7		The software documentation and the software design complies supplied by the manufacturer with the requirements of this standard.
Nominal activation conditions/Sensitivity:			
Directional dependence	4.3.1		The response time of the point dectetor do not unduly depend on the direction of airflow around the point heat detector.
Static response temperature	4.3.2		The response temperatures of the point heat detectors lie between the minimum and maximum static response temperatures, according to the category of the point heat detector in Table 1 above.
Response times from typical application temperature	4.3.3		The response times of the point heat detector lie between the lower and upper response time limits for the appropriate point heat detector category in Table 2 above.
Response times from 25 °C	4.3.4		The response time at 3 K min ⁻¹ exceeds 7 min 13 s and the response time at 20 K min ⁻¹ exceeds 1 min 0 s.





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Response times from high	4.3.5	No alarm or fault signal was given at high ambient
ambient temperature		temperatures appropriate to the anticipated service
		temepratures.
		A1
		3 K min ⁻¹ , Lower limit, 1 min 20 s and upper limit 13 m 40
		S.
		20 K min ⁻¹ , Lower limit, 12 s and upper limit 2 m 20 s.
Reproducibility	4.3.6	The response times of the point heat detectors lie
		between the lower ad upper response time limits
		specified in Table 2 above.
		opeomed in radio 2 address
Response delay (response		
time):		
Additional test for suffix S	4.4.1	N/A
	4.4.1	IV/A
point heat detectors	4.4.2	C. C. D. the weight heat detected and detected
Additional test for suffix R	4.4.2	Suffix R, the point heat detector maintains the
point heat detectors		response requirements of its category, in table 2
		above, for high rates of rise of temperature from an
		initial temperature below the typical application
		temperature applicable to the category marked on it.
		Point heat detector Initial conditioning
		category temperature °C
		A1R 5 ±2
Tolerance to supply		
voltage:		
Variation in supply	4.5	The point heat detector does not unduly depent on
parameters		variation in the supply parameters and lie between the
·		lower and upper response time limits specified in Table 2
		above.
Durability of nominal		
activation		
conditions/Sensitivity:		
temperature resistance		
Cold (operational)	4.6.1.1	No alarm or fault signal was given during the transition to
Cold (operational)	4.0.1.1	the conditioning temperature or during the period at the
		n i
		condition temperature
		Posponso time at 2 K mind was not less than 7 min 42
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1. 20 K min 1 a the 20 Link
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
Dry heat (endurance)	4.6.1.2	N/A for A1R.
Humidity resistance		
Damp heat, cyclic	4.6.2.1	No alarm or fault signal was given during the
(operational)		conditioning.
		Lower temperature: (25±3) °C
		Upper temperature: (40±2) °C
		Relative humidity:
		At lower temperature :≥ 95 %
		At upper temperature : (93 ±3) %
ı	1	1







П		
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min-1 was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
Damp heat, steady-state	4.6.2.2	No fault signal was given on reconnection attributable to
	4.0.2.2	
(endurance)		the endurance conditioning.
		Conditioning
		Temperature : 40 ±2 °C
		Relative Humidity: 93 ±3 %
		Duration : 21 days
		22 44/5
		Despense time at 2 K min-1 was not less than 7 min 12 s
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
		50 5 compared with the time obtained in 4.5.0
Complete		
Corrosion resistance		
Sulphur dioxide (SO ₂)	4.6.3	No fault signal was given on reconnection attributable to
corrosion (endurance)		the endurance conditioning.
		Conditioning
		Temperature : 25 ±2 °C
		·
		Relative Humidity: 93 ±3 %
		SO2 concentration: 25 ±5 ppm (by volume)
		Duration: 21 days
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min-1 was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
Vibration resistance		
	1.5.1.1	No. 1. C. Iv. 1. Iv. 11
Shock (operational)	4.6.4.1	No alarm or fault signal was given during the
		conditioning period or an additional 2 min.
		For specimen with a mass ≤ 4,75 kg:
		Shock pulse type: Half sine
		Pulse duration: 6 ms
		Peak acceleration: 10X (100-20M) ms-2 (M is specimen
		mass in Kg)
		Number of directions: 6
		Pulses per direction: 3
		Pachanca time at 2 K min-1 was not less than 7 min 12 a
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
		So sompared man are time obtained in note
	4 (4)	the algues and all the control of th
Impact (operational)	4.6.4.2	No alarm or fault signal was given during the
Impact (operational)	4.6.4.2	No alarm or fault signal was given during the conditioning period or an additional 2 min.







		Conditioning: Impact energy: 1,9 ±0,1 J Hammer velocity: 1,5 ±0,13 ms ⁻¹ Number of impacts: 1
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Vibration, sinusoidal (operational)	4.6.4.3	No fault signal was given during the conditioning Conditioning:
		Frequency range: 10 to 150 Hz Acceleration amplitude: 5 ms ⁻² (≈0,5 g _n) Number of axes: 3 Sweep rate: 1 octave min ⁻¹
		Number of sweep cycles: 1 per axis
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Vibration, sinusoidal (endurance)	4.6.4.4	No fault signal was given on reconnection attributable to the endurance conditioning.
		Conditioning: Frequency range: 10 to 150 Hz
		Acceleration amplitude: 10 ms ⁻² (≈1,0 g _n) Number of axes : 3
		Sweep rate: 1 octave min ⁻¹ Number of sweep cycles: 20 per axis
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Electrical stability EMC immunity (operational)	4.6.5	Compliance in EN 50130-4:2011 and No fault signal was given during the conditioning.
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6







Essential characteristics	Clauses in EN 54-7:2018	Regulatory classes	Performance
Operational reliability:	EN 34 7.2010	ciusses	
Individual alarm indication	4.2.1		The visual indicator(s) are visible from a distance of 6 m in an ambient light intensity up to 500 lx.
Connection of ancillary devices	4.2.2		Open or short circuit failures of connection to ancillary device did not prevent the correct operation of the detector
Monitoring of detachable detectors	4.2.3		A fault condition is signaled when the detector is removed from the mounting base.
Manufacturer's adjustments	4.2.4		It is not possible to adjust the detector settings without the use of a special tool to access into the detector or use of a code to enabling entry into the panel programming software.
On site adjustment of response behavior	4.2.5	None	The mode(s) of operation are adjustable from the Control and Indicating Equipment by use of a loop communication protocol. Access to enable mode changes is by software control of the protocol communication.
Protection against the ingress of foreign bodies	4.2.6		The chamber is designed so that a sphere of diameter (1,3±0,05) mm cannot pass into the sensor chamber.
Response to slowly developing fires	4.2.7		The provision of "drift compensation" (e.g. to compensate for sensor drift due to the build-up of dirt in the detector), does not lead to a significant reduction in the detectors sensitivity to slowly developing fires.
Software controlled detectors	4.2.8		The software documentation and the software design complies with the requirements of EN 54-7:2018.
Nominal activation conditions/sensitivity:		†	7.2020.
Repeatability	4.3.1		Ratio of response values $m_{max}:m_{min} \le 1.6$ Lower response value, $m_{max}:m_{min} \ge 0.05$ dB m ⁻¹
Directional dependence	4.3.2	Threshold	Ratio of response values $m_{max}:m_{min} \le 1.6$ Lower response value, $m_{max}:m_{min} \ge 0.05$ dB m ⁻¹
Reproducibility	4.3.3		Ratio of response values $m_{max}:\overline{m} \le 1.33$ Ratio of the response values $\overline{m}: m_{min} \le 1.5$







		Lower response value, m _{min} <u>></u> 0.05 dB m ⁻¹
Response delay (response time):		
Air movement	4.4.1	Ratio is > 0.0625 and < 1.60 and the point smoke detector did not emit a fault nor alarm signal during the test with aerosol-free air
Dazzling	4.4.2	The specimen did not emit neither an alarm nor a fault signal and Ratio of response thresholds m_{max} : $m_{min} \le 1.6$
Tolerance to supply voltage:		
Variation in supply parameters	4.5	Ratio of response values m_{max} : $m_{min} < 1.6$ Lower response value, $m_{min} \ge 0.05$ dB m ⁻¹
Performance parameters under fire conditions:		
Fire sensitivity	4.6	Evaluated as meeting the requirements of TF2 toTF5
Durability of nominal activation conditions/Sensitivity:		
temperature resistance		
Cold (operational)	4.7.1.1	The specimen did not emit neither an alarm nor a fault signal and Ratio of response values m _{max} :m _{min} ≤ 1.6
Dry heat (operational)	4.7.1.2	The specimen did not emit neither an alarm nor a fault signal and Ratio of response values m _{max} :m _{min} ≤ 1.6
Damp heat, steady-state (operational)	4.7.2.1	The specimen did not emit neither an alarm nor a fault signal and ratio of response values m _{max} :m _{min} ≤ 1.6
Damp heat, steady-state (endurance) Corrosion resistance	4.7.2.2	No fault signal, attributable to the endurance conditioning was given on reconnection of the specimen and Ratio of response values m_{max} : $m_{\text{min}} \leq 1.6$
Sulphur dioxide (SO ₂) corrosion (endurance)	4.7.3	No fault signal, attributable to the endurance conditioning was given on reconnection of the specimen and Ratio of response values m _{max} :m _{min} ≤ 1.6
Vibration resistance		
Shock (operational)	4.7.4.1	No fault signal given from the specimen during the conditioning period or the additional 2 min. and Ratio of response values $m_{\text{max}} : m_{\text{min}} \leq 1.6$
Impact (operational)	4.7.4.2	No fault signal given from the specimen during the conditioning period or the additional 2 min. and Ratio of response values $m_{\text{max}} : m_{\text{min}} \leq 1.6$







Vibration, sinusoidal (operational)	4.7.4.3	No fault signal given from the specimen during the conditioning and Ratio of response values m_{max} : $m_{min} \le 1.6$
Vibration, sinusoidal (endurance)	4.7.4.4	No fault signal, attributable to the endurance conditioning was given on reconnection of the specimen and Ratio of response values m_{max} : $m_{\text{min}} \le 1.6$
Electrical stability EMC immunity (operational)	4.7.5	
a) Electrostatic discharge (operational)		
b) Radiated electromagnetic fields (operational)		No alarm or fault signal given during the conditioning and Ratio
c) Conducted disturbances(operational)		of response values m _{max} :m _{min} ≤ 1.6
d) Fast transient bursts (operational)		
e) Slow high energy voltage surge (operational)		

Annex 2

TEST DOCUMENTATION

Accredited Laborat	tory Report no.	Date
BRE	TE 295788-SW	2014-10-15
BRE	P101798 Issue: 1	2015-10-23
BRE	TE295788-1	2015-04-30
BRE	AB-P123581	2023-01-17

TECHNICAL BASIS

File Number		Title
SA5000-700	Build Standard	
SA5000-200	Build Standard	
45681-210	Build Standard	



